Introduction to Causal Inference from an Observational Study for a Single Time Point Intervention

Michael Rosenblum

Department of Biostatistics

February 28, 2017



Outline

- Definition of Causal Effects and 2 Examples
- Assumptions Needed to Identify Causal Effects from Observed Data Distribution
- Estimation Methods and Assumptions Needed for Consistency of Estimators
- Computing Standard Errors (using bootstrap)
- O Potential Challenges You May Encounter

Definitions and Goal

- X=Baseline Variables, Z=Binary treatment or Exposure, Y=Outcome.
- Observed Data Structure: (X_i, Z_i, Y_i) for each study participant i = 1, ..., n.
- Goal is to estimate the effect of the treatment/exposure on the outcome.
- We focus on population average treatment effect (abbreviated ATE), a contrast between what the mean outcome would be if everyone in population were assigned to treatment versus everyone assigned to control.
- Main challenges we address: how to account for measured confounding
- We assume no unmeasured confounding (i.e., X contains all confounders)



Example 1

- · Population: HIV infected individuals; Data from cohort study.
- X=age, sex, ART-naive; Z=Indicator of Adherence > 50% to Antiretroviral Therapy during month; Y=Indicator of Virologic Failure.
- Data structure: observe (X_i, Z_i, Y_i) for each study participant *i*

Example 2

- Population: individuals with intracerebral hemorrhage (ICH); data from randomized trial
- X=ICH volume, ICH location, age, NIH Stroke Scale;
 Z=Indicator of Received Surgical Intervention; Y=Modified Rankin Scale < 4 at 180 days.
- Data structure: observe (X_i, Z_i, Y_i) for each study participant *i*

Main Challenge

- X=Baseline Variables, Z=Binary treatment or Exposure, Y=Outcome.
- Observed Data Structure: (X_i, Z_i, Y_i) for each study participant i = 1, ..., n.
- Problem in observational study: those with Z=1 may not be comparable to those with Z=0 in baseline characteristics related to Y.
- Difference in sample proportions with Y = 1 comparing Z=1 and Z=0 groups can have confounding/selection bias for estimating ATE.



Need to Introduce Potential Outcomes

- Potential outcomes Y_0 , Y_1 , i.e., outcome **under assignment** to Z = 0, 1, respectively.
- Goal is to estimate causal effect, e.g., difference of proportions $P[Y_1 = 1] P[Y_0 = 1]$ $P[Y_0 = 1]$ is population proportion under hypothetical intervention where everyone **assigned** Z = 0. $P[Y_1 = 1]$ is population proportion under hypothetical intervention where everyone **assigned** Z = 1.
- The fundamental challenge of causal inference: only one of Y₀, Y₁ is observed for each person, i.e., the one corresponding to their Z value.
- Therefore, half the potential outcomes are missing. Goal is inferences about *Y*₀ and *Y*₁ in a hypothetical population where none of these missing.
- If there are confounders, then $P[Y = 1 | Z = 1] \neq P[Y_1 = 1]$.

Defining Causal Effect using Potential Outcomes

- Potential outcomes Y_0 , Y_1 , i.e., outcome **under assignment** to Z = 0, 1, respectively.
- Goal is to estimate causal effect, e.g., risk difference $P[Y_1 = 1] - P[Y_0 = 1]$, risk ratio $P[Y_1 = 1]/P[Y_0 = 1]$, log odds ratio logit[$P(Y_1 = 1)$] - logit[$P(Y_0 = 1)$] where logit(x) = log[x/(1 - x)].
- Note: $expit = logit^{-1}$.



Note on Interpretation of Conditioning

- P[Y = 1|Z = 1] is read as "Probability of Y=1 GIVEN (conditioned on) Z=1".
- "GIVEN" can be interpreted as "among those in the population with" or "among strata with"
- P[Y = 1 | Z = 1] is read as "Probability of Y equals 1 among strata with Z=1"
- P[Y = 1 | Z = 1, X = x] is read as "Probability of Y=1 among strata with Z=1, X=x"
- The above are population quantities, which we could in principle learn by measuring (X, Z, Y) on everyone in the population; in practice we just get a sample from the population and try to infer from this about the population.



Assumptions

- X=Baseline Variables, Z=Binary treatment, Y=Outcome.
- Goal is to estimate causal effect, e.g., $P[Y_1 = 1] P[Y_0 = 1]$.
- Key assumptions that allow identifiability of causal effect based on observed data distribution:
 - Consistency: $Y = Y_Z = (1 Z)Y_0 + ZY_1$ (connects observed and potential outcomes)
 - Strong ignorability: *Y*₀, *Y*₁ independent of *Z* given *X*. Also called: no unmeasured confounders assumption (i.e., *X* has all confounders). Roughly speaking, confounder of effect of *Z* on *Y* is a variable that impacts both.
 - Experimental Treatment Assignment (ETA): P(Z|X)>0, i.e., no stratum of X where exposure/non-exposure impossible.
 - Assume each triple (*X_i*, *Z_i*, *Y_i*) is independent, identically distributed draw from unknown joint distribution *P*_{*X*,*Z*,*Y*}.
 - Let \mathcal{X} denote all possible values of X.
- For clarity of presentation we estimate one of $P[Y_1 = 1]$, $P[Y_0 = 1]$ at a time. Can then plug into the desired contrast.



Identifiability of Causal Effects from Observational Data

Goal: Estimate $P(Y_1 = 1)$, which under the assumptions of consistency and ignorability, equals

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid Z=1, X=x) P(X=x).$$

This follows from:

$$P(Y_{1} = 1)$$

$$= \sum_{x \in \mathcal{X}} P(Y_{1} = 1 | X = x) P(X = x)$$

$$= \sum_{x \in \mathcal{X}} P(Y_{1} = 1 | X = x, Z = 1) P(X = x) \text{ (by ignorability)}$$

$$= \sum_{x \in \mathcal{X}} P(Y = 1 | X = x, Z = 1) P(X = x) \text{ (by consistency).}$$

We expressed $P(Y_1 = 1)$ in terms of observed data distribution.



Identifiability of Causal Effects from Observational Data

Goal: Estimate $P(Y_1 = 1)$, which under the assumptions of consistency and ignorability, equals

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid Z=1, X=x) P(X=x).$$

Can do similarly to estimate $P(Y_0 = 1)$ by changing to Z = 0 in above.

Note: in general

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid Z=1, X=x) P(X=x) \qquad \neq \qquad P(Y=1 \mid Z=1).$$

This is because in general $P(X = x | Z = 1) \neq P(X = x)$ due to selection bias.

Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid Z=1, X=x) P(X=x).$$

- Standardization (a.k.a. g-computation) Fit outcome regression working model $m_1(X, \alpha)$ for P(Y = 1 | Z = 1, X). Estimator is $\frac{1}{n} \sum_{i=1}^{n} m_1(X_i, \hat{\alpha})$.
- Inverse Probability Weighting (Horvitz-Thompson): Fit working model $g_1(X, \gamma)$ for P(Z = 1 | X). Estimator is $\frac{1}{n} \sum_{i=1}^{n} Z_i Y_i / g_1(X_i, \hat{\gamma})$.
- **Ouble Robust Estimator:** Involves fitting both models. Many options. E.g., if both models are logistic regression, first fit g_1 , then fit m_1 using weights $1/g_1(X_i, \hat{\gamma})$ and denote fitted coefficients by $\bar{\alpha}$. Estimator is $\frac{1}{n} \sum_{i=1}^{n} m_1(X_i, \bar{\alpha})$. (Due to Marshall Joffe.)



Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid X=x, Z=1) P(X=x).$$

Requirements for consistency of estimators:

- Standardization (a.k.a. g-computation) Outcome regression working model m₁(X, α) for P(Y = 1 | Z = 1, X) must be correctly specified.
- Inverse Probability Weighting: Propensity score working model $g_1(X, \gamma)$ for P(Z = 1 | X) must be correctly specified.
- Double Robust Estimator: Involves fitting both models. At least one working model must be correctly specified.

Note: our ultimate goal is to estimate causal effect, not coefficient vectors α, γ . Causal effect is generally not equal to any of these coefficients.



Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid X=x, Z=1)P(X=x).$$

Standardization: Fit a logistic regression model m₁(X, α) for P(Y = 1 | Z = 1, X) (using only those with Z = 1). Estimator is ¹/_n ∑ⁿ_{i=1} m₁(X_i, α̂). That is, the empirical average, over all subjects (even those with Z = 0) of their predicted outcomes if they'd gotten Z = 1, based only on their baseline variables X_i, using the outcome regression model fit. For example, if you fit model

$$P(Y = 1 | Z = 1, X) = expit(\alpha_0 + \alpha_1 X + \alpha_2 X^2),$$

this estimator is: $\frac{1}{n} \sum_{i=1}^{n} \operatorname{expit}(\hat{\alpha}_0 + \hat{\alpha}_1 X_i + \hat{\alpha}_2 X_i^2)$.

Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid X=x, Z=1) P(X=x).$$

 Inverse Weighted Estimator (also called IPW, IPTW): Fit a logistic regression model g₁(X, γ) for P(Z = 1|X) using all participants; this is called propensity score model. Estimator is ¹/_n Σⁿ_{i=1} Z_iY_i/g₁(X_i, γ̂). For example, if you fit model

$$P(Z=1|X) = \exp(\gamma_0 + \gamma_1 X + \gamma_2 X^2),$$

this estimator is: $\frac{1}{n} \sum_{i=1}^{n} Z_i Y_i / \exp(\hat{\gamma}_0 + \hat{\gamma}_1 X_i + \hat{\gamma}_2 X_i^2)$.



Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid X=x, Z=1) P(X=x).$$

Double Robust Estimator of Joffe: First fit propensity score logistic regression model g₁(X, γ). Next, fit outcome regression logistic regression model m₁(X, α) using weights 1/g₁(X_i, γ̂) and denote fitted coefficients by ᾱ. Estimator is ¹/_n Σⁿ_{i=1} m₁(X_i, ᾱ).



Goal: Estimate $P(Y_1 = 1)$, which was shown to equal

$$\sum_{x\in\mathcal{X}} P(Y=1 \mid X=x, Z=1) P(X=x).$$

Another Double Robust Estimator: Fit g_1 , then fit logistic regression model m_1 with additional term $Z/g_1(X, \hat{\gamma})$. Estimator is $\frac{1}{n} \sum_{i=1}^{n} m_1(X_i, \hat{\alpha})$.



Computing Standard Errors for Various Estimators

Consider any of the above estimators we've discussed. In general, can use nonparametric bootstrap to estimate the standard error, when data has sample size n:

- Repeatedly (say, 10,000 times) resample *n* units with replacement from your data set to created a replicated data set of size *n*.
- Compute estimator on replicated data set.
- Compute the standard deviation of the 10,000 estimates-this is the estimate of the standard error.

Note: for each replicated data set, when computing the estimator, you should refit the models. This captures the variability due to the model parameters being estimated rather than known a priori. Recommendation: use BCa method for confidence interval.

Potential Challenges

- Very small estimated values of P(Z = z|X); called "practical Experimental Treatment Assignment violation". Leads to very large weights. May need to truncate weights; or can modify the quantity being estimated.
- Too many variables to adjust for and not enough participants n. Watch out for model overfit.
- Assumption Violations (which can be hard or sometimes impossible to detect)



References:

- Scharfstein DO, Rotnitzky A, Robins JM. Adjusting for non-ignorable drop-out using semiparametric non-response models (with discussion). Journal of the American Statistical Association 1999; 94:1096–1146.
- van der Laan, M. J. and D. Rubin (2006, October). Targeted Maximum Likelihood Learning. The International Journal of Biostatistics 2 (1).
- Robins JM, Sued M, Lei-Gomez Q, Rotnizky A. Comment: performance of double-robust estimators when inverse probability weights are highly variable. Statistical Science 2007; 22(4):544–559.
- Robins JM, Sued M, Lei-Gomez Q, Rotnitzky A. Double-robustness with improved efficiency in missing and causal inference models. Technical Report, Harvard School of Public Health, 2007

Acknowledgments: Slides are from a course co-taught with Constantine Frangakis.

Thank you to Jacob Fiksel who provided this beamer template.

